ECE 381: Microcontrollers

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Web Site:

http://www.siue.edu/~tyork/classes/ece381



1st Class: What are we going to do?

- Necessary class business stuff (syllabus, schedule, office hours)
- Introduction to microcontrollers
- Intro. to the Cypress PSoC (Programmable Systemon-a-Chip) which will be what we use for this class
 - Get set up in lab
 - Choose partners
 - Pick a station
 - Get a PSoC Dev Kit



What I Expect of You

- Class syllabus: http://www.siue.edu/~tyork/classes/ece381/syllabus.pdf
- Highlights:
 - 50% of grade is labs, 30% exams, 15% final project, 5% class participation/other homework
 - Class Attendance is (Mostly) Mandatory!
 - Notify me if you can't make it (job, illness, life event, etc.)
 - · Open lab sessions are not mandatory if you have already demoed
 - There will be readings, from both book and datasheets (Over course of semester, I hope you learn how to properly read a datasheet!)
 - Work in pairs on labs, but turn in separate reports (report format: http://www.siue.edu/~tyork/classes/ece381/labReportFormat.html)
- No set lab time!
 - Unlike other classes, labs will take longer than 3hr session, plan accordingly
 - Once I know more about parts kits, I'll know whether or not you get to keep the PSoC5 kit.
 UnitI then, leave it in lab.



ECE 381 Microcontrollers – Spring 2017 Schedule				
Week	Lecture/Activity	Lab Assignment	In Lab	Submit
1	Overview / C Language Primer	Lab 1 – Introduction		
	General Purpose I/O	Lab 2 – Polling and the LCD	Lab 1 Demo	
2	Interrupts	Lab 3 – Interrupts and Rotary Encoders	Lab 2 Demo	
	PSoC5 Schematic Editor and Modules			Lab 2 Report
3	Lab 4 Overview	Lab 4 – Square Wave Generator	Lab 3 Demo	
	The RS232 Interface and Protocol			Lab 3 Report
4	Lab 5 Overview	Lab 5 – RS232 Interfacing	Lab 4 Demo	
	Class convenes in lab			Lab 4 Report
5	Exam 1			
	Lab 6 Overview	Lab 6 – I2C External RAM	Lab 5 Demo	
6	Class convenes in lab			Lab 5 Report
	USB Basics			
7	Lab 7 Overview	Lab 7 – Thermostat & Stepper Motors	Lab 6 Demo	
	Class convenes in lab			Lab 6 Report
8	PS/2 Keyboard Protocol / Bitbanging			
	Class convenes in lab		Lab 7 Demo	
9	Lab 8 Overview	Lab 8 – PS/2 Keyboard Interface		
	The PSoC5 Analog System			Lab 7 Report
10	Lab 9 Overview	Lab 9 – Wireless Temperature Sensor	Lab 8 Demo	
	SPI Protocol and Interfacing			
11	Lab 10 Overview	Lab 10 – SPI SRAM Interface	Lab 9 Demo	Lab 8 Report
	Exam 2			
12	The Final Project			
	ADCs & DACs	Lab 11 – Data Acquisition System	Lab 10 Demo	Proposal/9 Report
13	Class convenes in lab			
	Final Project Assignment			
14	Class convenes in lab	Begin Work on Final Project	Lab 11 Demo	
	Class convenes in lab			
15	Class convenes in lab			Lab 11 Report
	Class convenes in lab			
Finals			Project Demo	Project Report

Lab Things That Might Be Useful

- Wire Strippers/Clippers
- Micro USB Cable



What is a Microcontroller?

- Book: "A processor, memory (ROM & RAM), and general purpose I/O integrated on a single chip."
- Examples: PSoC (of course), TI MSP430, Parallax Propeller, Atmel AVR (Arduino), Freescale HCS12, Coldfire
- Keyword: "Controller"
 - Interface with external devices/circuits/components through GPIO, ADCs, various communicatoin buses
 - Do some simple processing
 - Control other devices/circuits/components through GPIO



Virtually Every µC Does These Things Too

- Interrupts
 - "Every X milliseconds, run Y code..."
 - "When Bit 0 of Port 1 goes high..."
- Precision Timers & Counters
 - "Master CLK at 24 MHz, divide by A, then divide by B"
 - Watchdog timers "If watchdog not reset, initiate recovery"
- Analog Inputs (ADCs)
- Pulse Width Modulation



Other µC Things

- Registers, lots of registers
 - Data registers, data direction registers, condition code registers, timer control registers, etc.
 - Setup/input/output involve reading and writing to registers
- Memory Map: Which data goes where
 - i.e. Registers (0x0000-0x00ff), SRAM (0x0100-0x0FFF),
 ROM/Flash (0x1000-0x1CFF), Vectors (0x1D00-0x1FFF)
- Internal registers
 - Accumulators
 - Program Counter, Inst. Reg., Stack Pointer, etc.



The PsoC5 (CY8C5888LTI-LP097)

- 32-bit ARM Cortex-M3 core plus DMA controller and digital filter processor, at up to 80 MHz
 256KB Flash, 32KB ECC Flash, 2KB EEPROM, 64KB RAM
- http://www.cypress.com/file/45906/download -Datasheet



Assembly Language

Ultimately, all programs are composed in assembly

```
ORG 0 \times 0100
                 ;Start program at first address in ROM
   LDAA #0xFF
                 ;Load accumulator A with 0xFF (all 1's)
   STAA 0x01
                 ;Store in Data Direction register
                 ; (address = 0x01) for Port0 (1 makes bit an
                 ; output)
   CLRA
                 ;Clear Accumulator A
MAIN
   STAA
          0x00; Store A to address 0x00 (Port0)
   INCA
                 :Increment Accumulator A
   BRAMAIN
                 ; Always branch back to MAIN
```



Higher Level Language

 C is a high level language typically used for programming (We will be using C for the PSoC)



• C is a typed language:

- char, int, short, unsigned, float, etc. are types
- Each defines a space in memory (data) of a defined size and an address (pointer)
- PSoC Defines BYTE (unsigned char), WORD (unsigned int)
- PSoC5 Sizes (NOTE: THESE ARE DIFFERENT FROM MOST STD C):
 - char (1 byte)
 - int (4 bytes)
 - unsigned (4 bytes)
 - float (4 bytes) NOTE: The PSoC5 Does NOT have a hardware FP unit. All fp done in software → SLOW!

C uses pointers

- int * var vs. int var
- Pointers are memory locations only, can POINT to variables or storage
- int var1
 - · &var1 is a pointer to the address of var1
 - *var1 is the value at the address of var1



- Beware of where variables declared!
- PSoC expects all variables declared before executable code!

```
//Header file for microcontroller
#include <uconAPI.h>
                        //Defines PORTO and PORTO DDR
                      Global Space (Before Functions): Accessible to All
int globalVar;
void main()
                      Local Space (In Functions): Only accessible
   int localVar;
                      to function
   PORTO DDR = 255; //Set PORTO to be all outputs
   PORTO = 0; //Initialize PORTO to be 0
   while (1) { //Main loop
       PORTO += 1; //Increment PORTO
```

Pass by value vs. Pass by reference

```
#include <uconAPI.h> //Header file for microcontroller
void func1(int *_var)
   *var++;
                          By reference (directly modifies variable value)
int func2(int var)
                         By value (makes local copy)
   return var +
void main()
   int localVar = 0:
   int retVar;
                                 localVar = 1 after this
   func1(&localVar);
   retVar = func2(localVar);
                                           localVar still = 1 after this,
                                           retVar = 2
```

- Arrays are contiguous blocks of memory with same type
 - char str1[16] ← 16 consecutive chars in memory
 - int var[8] ← 8 consecutive ints in memory
- Access individual elements through [] notation

```
str1[0] = 'H';str1[10] = 'i';var[2] = var[1] + var[0];
```

- Array name is really a pointer to first location
 - str1[10] equivalent to address of str1 + 10 bytes of memory
 - &str1[10] gives memory address of 10th element (str1[10] gives data)
 - Pass arrays to function by reference only
 - func(str1) only works if func declared as: void func(char * array)
 - · Doesn't make a local copy since passed by reference



- Strings are arrays of characters
- Last element of string is special '\0' or NULL character, denotes end of string
 - ie. char str[16] = $\{'H', 'e', 'l', 'l', 'o', '\setminus 0'\}$
 - printf(str) → Hello



```
• C has if, else if, else conditional statements
```

```
- if (var == 1) {
    do something for var == 1
}
else if (var == 2) {
    do something for var == 2
}
else {
    do something for var not 1 or 2
}
```

C also has switch-case statement for conditionals

```
- switch(var) {
    case 1:
    do something for var==1
    break;
    case 2:
    do something for var==2
    break;
    default:
    do something for var not 1 or 2
    break;
}
```

Cases must be terminated by breaks



• Loops can be done with while, do...while, and for

```
- while (var < 10) {</p>
      var++;
- do {
      var++;
  } while(var < 10);</pre>
- for (var = 0; var < 10; var++){
     var1 = var;
```



- Every program has to have a main() function
 - This is essentially the code that gets executed when the uC gets turned on (sometimes after some backend setup)
 - For uCs, there is always an infinite loop somewhere in main
- Other functions can be declared in a .h file
 - Just the prototype
 - Code goes in a .c file of same name with same name as prototype
 - This way, compiler only has to recompile if changes to .c file or .h file
 - These .c & .h files can be exported easily to other projects



Assignments

Reading:

- Cady, Ch. 2
- CY8C5888LTI-LP097 Data Sheet (labs/files/PSoC Technical Documents/psoc5_CY8C5888LTI-LP097.pdf)
- PSoC5 Architecture Technical Reference Manual (labs/files/PSoC Technical Documents/PSoC5LP_Architecture_TRM.pdf)
- PSoC5 Prototyping Kit Guide (/labs/files/PSoC Technical Documents/CY8CKIT_059 PSoC 5LP Protoyping Kit Guide.pdf)
- Lab 1: Introduction
 - 1a: Step-by-step instructions to blink the onboard LED
 - 1b: Write own simple program to make Port1 a counter

