CVIPtools: A Software Package for Computer Imaging Education

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ABSTRACT: New computer imaging software is described. CVIPtools illustrates principles of computer imaging and enables rapid development of complex algorithms. The easy-to-use graphical user interface makes available over 170 functions to students and artists, astronomers, geographers, and others who want to explore imaging but lack programming knowledge. © 1997 John Wiley & Sons, Inc. Comput Appl Eng Educ 5: 213–220, 1997

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INTRODUCTION

Computer Vision and Image Processing tools (CVIPtools) [1] is a software package used in teaching computer imaging to undergraduate and graduate students at Southern Illinois University at Edwardsville (SIUE). Developed over the past 5 years at SIUE, CVIPtools is used both as an adjunct to traditional laboratory exercises and as a research tool that allows students to contribute their work to the ongoing project. Soon to be distributed free over the World Wide Web, CVIPtools presents more than 170 functions and algorithms organized into five main categories, in a windowed program that is easy

for even a nonprogramming user to operate. Fast algorithms and the automatic display of processed images provide immediate feedback to the user, thus reinforcing classroom lectures and tutorials provided with lab exercises.

BACKGROUND

CVIPtools was conceived by one of the authors (S.E.U.) after his doctoral work at the University of Missouri–Rolla, where he developed an image-processing color segmentation method for use in the automatic evaluation of skin tumors in humans [2]. At that time, no single generic program existed that made available a large number of commonly used functions and algorithms to researchers in the fields of image processing and computer vision. Existing programs were typically hardware specific; commercial packages offered an extremely small number of tools useful for researchers. The author found that a majority of his research time was spent in

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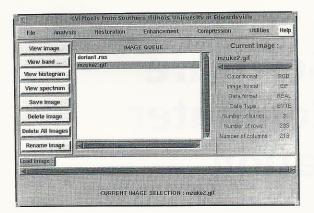


Figure 1 The main window for CVIPtools. Data for the selected (highlighted) image are displayed on the right side of the window.

writing computer code to perform algorithms and basic functions. CVIPtools was designed to provide a large number of basic and advanced operations to the nonprogramming user. Originally written as a textual menu-driven program, it was converted to its current windowed format in 1996 [3].

While CVIPtools has been designed and developed by the research team at the Computer Vision and Image Processing Laboratory at SIUE, funded by various grants, some elements of the program have been developed in fulfillment of students' master's projects [3–7]. CVIPtools contains one window (Feature Extraction) developed cooperatively by the students in a one-semester graduate course. The program is continually upgraded as new functions and algorithms are implemented in C-language routines. Work is under way to port the program from its native UNIX form to other platforms.

INTERFACE

The graphical user interface (GUI) for CVIPtools allows even those not familiar with computer imaging to experiment with sophisticated techniques. The GUI is easy to use because it operates in accordance with accepted principles of interface design [8,9]. Four important principles that underlie interface design are as follows: Consider the user's mental model of the task, maintain compatibility with other programs, maintain internal consistency, and use color sparingly. All users, regardless of their degree of knowledge of computer programming practices, have expectations as to how the program accomplishes its tasks. If the program operates in a

fashion similar to that of the user's model, fewer errors will result. Because many users of CVIPtools are familiar with at least one or two other windowed programs, CVIPtools windows were designed with a menubar at top, messages near the bottom, and the functional area in the center. As the work flows from window to window within the program, standardized placement and use of buttons, command words, and methods of operating the functions maintain the required internal consistency. Finally, the use of color has been kept to a minimum in the program to avoid forcing the user to remember associations between a color and its meaning within the program, and to avoid the inconsistent display of colors that can occur on different computer systems.

The main, or root, screen for the program is shown in Figure 1. Operations that are common to all windows, such as loading, viewing, and renaming images, are located in the root window. The IMAGE QUEUE area lists images loaded by the user and those that result from operation of the program. Selection of an image on the list displays its basic image data and makes the selected image available to all functions for processing.

Choosing one of the major functional categories listed across the top of the window, Analysis, Restoration, Enhancement, Compression, or Utilities, causes that category's selection bar window to appear. All five major category selection bars can be

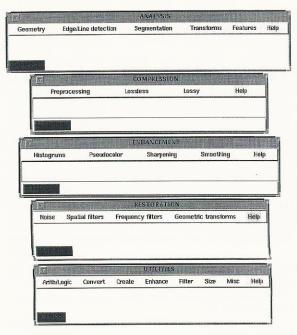


Figure 2 The selection bars for the five main function categories show the subcategories available to the user.

	ANA	LYSIS -> Segment	ation		
Geometry Edge/	Line detection	Segmentation	Transforms	Features	Help
🌣 Fuzzy C Mean, with ti	he Gaussian kem	el variance (0 - 20.0):		
Gray Level Quantizati	on, with the num	ber of gray levels:	→ Stan → IGS	dard	
 Histogram Thresholding 	ıg				
Median Cut, with the	number of desire	d colors (2 -1000):			
PCT/Median, with the	number of desir	ed colors (2-1000):			
SCT/Center, with the	number of color	s along A axis:	and B axis:		
Multi_Resolution					
→ Pure uniformity→ Variance□ PCT		ean vs. global mean d gray level distance Thresl		d. vs. global homogeneity Percentage	,
Split and Merge				- 0	
		ean vs. global mean d gray level distance		ld. vs. global homogeneit	
☐ PCT	Entr	y level: 3 Thr	eshold: 50	Percentage	0.70
Morphological Filters					
	ening 💠 Erosio	n 💠 Dilation 💠 H	erative Modificat	ion (Binary ii	nage on
Kernel type: rectan	gle	ize: 3 ↓ He	eight: 3	Width	3
Current image is : mzuki	e2.gif				
DISMISSE					PERFO

Figure 3 The segmentation window in CVIPtools. No parameters are required for histogram thresholding, the selected segmentation method.

onscreen at one time (Fig. 2), simplifying the locating of a needed function.

Choosing a subcategory from a selection bar causes that window to expand and display the available functions. Figure 3 shows the available segmentation functions within the Analysis window.

A help screen is available within the program, organized into the same categories available from the root window. The help pages list the required and optional parameters for functions in the selected subcategory and detail methods that can be used to enter the values. Additional help is available outside the program through the use of the UNIX *man* command, which can display a complete manual page of each CVIPtools function. During the program's operation, if the user's action will be irreversible, such as in deleting all the images at one time, confirmation to proceed is required with a pop-up alert message. An alert box is also used to notify the user of improper value selections or other program errors. Figure 4 shows sample alert boxes.

USE IN LABORATORY EXERCISES

The primary use of CVIPtools is as an adjunct to computer imaging courses within the electrical engineering department at SIUE. Laboratory exercises, tutorials, and a sample menu-driven C-language program are provided students to guide them toward an understanding of the methods and tools used in computer imaging. Classroom lectures introduce topics that are illustrated and reinforced in the lab exercises. The students add their own C-code routines to a sample program, then check the accuracy of their work by comparing the output of their program against that of the same function in CVIPtools. Tutorials make extensive use of CVIPtools, allowing the students to quickly view the results of making incremental changes to function parameters.

The nonprogramming laboratory exercises used in the imaging courses are of the form of the following example. The input and resultant images follow the text.

Lab Exercise

This exercise illustrates the effects of low-pass filtering on a real image and compares the effects of ideal filtering to those of Butterworth filters.

(a) Load a 256 × 256 complex gray-scale image (Fig. 5) and perform the FFT on it. Use a blocksize of 256. Filter the transformed image using an ideal low-pass filter with a cut-off of 32. Keep the DC value. The program will automatically perform the inverse trans-

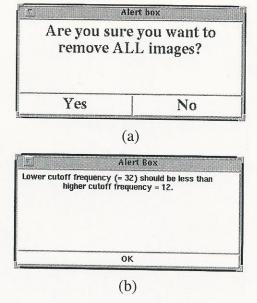
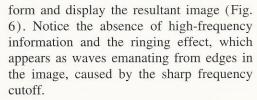


Figure 4 (a) Confirmation is required before deleting all images at one time. (b) Parameter error message specifies the exact problem.



Figure 5 Original image.



(b) Now apply a Butterworth low-pass filter of order 1 to the Fourier-transformed image. Use the same cutoff as in (a). Keep the DC



Figure 6 Ideal filtering; cutoff frequency, 32.



Figure 7 Butterworth filtering; cutoff frequency, 32; order, 1.

- during filtering. Compare the result (Fig. 7) with that of (a). Is the ringing effect as noticeable now? Why/why not?
- (c) Repeat (b) using an eighth-order Butterworth filter instead of a first-order filter. Compare the result (Fig. 8) to the results in (a) and (b). Because the frequency response of an eighth-order Butterworth filter is close



Figure 8 Butterworth filtering; cutoff frequency, 32; order, 8.

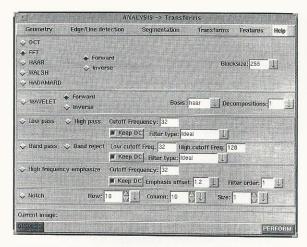


Figure 9 The transforms window in CVIPtools. Both transforms and transform filtering are available within the same window.

to that of an ideal filter, the image should be similar to that of (a).

Students use the Transforms subcategory of the Analysis window to perform the FFT (Fast-Fourier Transform) and the filtering called for in the exercise. The Transforms window is shown in Figure 9.

The ease of use of the GUI contributes to the success of the lab tutorials and exercises. For example, changing from the ideal low-pass to the Butterworth filter in the Transforms window is accomplished by clicking on the downward-pointing arrow to the right of "Filter type:" and selecting "Butterworth" from a pop-up list. Because changes are so easy to make and results are quickly displayed on the computer monitor, students often experiment more than called for in the exercises. Such experimentation was one of the desired results of the conversion of the program from its early text-based menu format to the current graphical interface form.

The CVIPtools project has attracted many students to the image processing and computer vision courses at SIUE. Beyond providing the usual satisfaction found in acquiring knowledge of a new field, the courses and CVIPtools offer students the opportunity to contribute their work to the project and see that work added to the software. The students in one graduate computer vision course cooperated in the creation of the feature extraction facility (Fig. 10) within CVIPtools. Research by some of the students concerning which features to extract was passed to others for implementation in C-language routines. Two students designed and constructed the

window, and implemented the code needed to select a desired object within an image by using a mouse. A help page was written for the functions, and the entire window was integrated into the CVIPtools program.

CVIPtools is beginning to see use outside the Engineering Department at SIUE. Students in geography and computer courses, along with people having an interest in astronomy, biology, and art, are discovering applications of CVIPtools to their fields of interest. Self-study is facilitated by the ease of operating the GUI, and results are immediately available to the user. At a few selected sites outside the university, CVIPtools is being used by working professionals to preprocess substandard images for use with specialized computer applications.

USE IN APPLICATION PROJECT DEVELOPMENT

Another area of use for CVIPtools is in the development of application-specific algorithms. For example, in digital image-processing courses, projects often center on image improvement methods based on restoration or enhancement techniques. Figure 11 shows the RESTORATION → Frequency filter

F		NALYSIS -> Featur	res		
Geometry Edg	e/Line detection	Segmentation	Transforms	Features	Help
Original image:				,	
Segmented image:	evolumental de la constance				
Feature file name:		View Fe	ature File	View Labeled In	nage
Class (optional):	The cr	The coordinates of the current object are : row , column			
	BINA	RY OBJECT FEATUR	ES		
		Select All			
∫ Area	Centroid	☐ Orie	entation	☐ Perimeter	
☐ Euler number	Projection	s Thir	iness	☐ Aspect r	atio
For pro	jections, enter the r	normalizing height: 10	and widt	h: 10	
	HIS	STOGRAM FEATURES	s		
☐ Mean	☐ Std Dev	☐ Skew	☐ Energy	□ Ent	гору
∏" Get	SI Spectral Features	PECTRAL FEATURES Number of Rings:	Number of S	Sectors:	
	RST-INVARIA	NT MOMENT-BASED Select All	FEATURES		
□rsti □rst	2 rst3	∫ Frst4	∏rst5 ⊓	Trst6	rst7
	ī	EXTURE FEATURES Select All			
☐ Energy	T Inertia	Correlation	☐ Inverse Di	ſſ	ру
Seimeid				Ĭ	ERFORI

Figure 10 The feature extraction window in CVIPtools, designed and implemented by graduate students taking a one-semester course.

4		RESTORATION -> Freque	ncy filters			
Noise	Spatial filters	Frequency filters	Geometric transforms	Help		
RESTORATION FILTERS Inverse Geometric Mean Power Spectrum Equalization		Degradation function:	mage:			
 Constrained Wener Practical Wi 	Constrained Least Squares	Mask height: 3 1	Mask width: 9	STATE OF THE PARTY		
G- 0		Outoff frequency: 12 1 if denominator = 0 : \bullet Let $R(u,v) = 1$ \Rightarrow Let $R(u,v) = 0$ Noise image: 0 original image:				
		Gamma: 1				
The generalized	restoration equati	on: $R(u,v) = \left[\frac{H^*(u,v)}{ H(u,v) ^2}\right]$	$\propto \left[\frac{H^*(u,v)}{\left[H(u,v)\right]^2 + \gamma \left[\frac{S_n(u,v)}{S_i(u,v)}\right]} \right]$	1-∝		
√ Notch Se	elect a transform					
Current image:						
DISMISS				PERFOR		

Figure 11 The frequency filter window in CVIPtools is one of four restoration screens.

window for CVIPtools; an Enhancement window, Histograms, is shown in Figure 12.

With the easy-to-use GUI-based program, students can develop algorithms experimentally. Various sequences of operations can be compared and contrasted quickly, allowing for extensive fine-tuning before any code is written. Once an algorithm has been developed, the student can rapidly create the application program because all functions within CVIPtools are accessible to C-language programmers through function libraries. Programmers can reference a manual page to obtain function prototypes, required parameters, and examples of a func-

	ns
Histograms Pseudocolor Sharpening	Smoothing Help
🔷 Histogram equalization on band: 💸 Value 🔷 F	ed 💸 Green 💸 Blue
	\downarrow 1
⇒ Histogram shrink to a lower limit: 0	an upper limit: 255
↓ Local equalization on band: ♠ Red ❖ Green ❖ Blu ↓ Adaptive - contrast ↓ Local gain ractor: 0.8 ↓ Local gain min: 5 ↓ ↓ Local mean factor: 1.0 ↓ Kernel st.	Local gain max: 10 🗼
→ Histogram specification Formula for gray image or red band: sin(0.025*x)	↓ Clear Function
Formula for green band: ramp(2.0"x+5)	↓ Clear Function
Formula for blue band: exp(0.025'x)	↓ Clear Function
↓ Linear modify Range: start 0 end 255 initial value ★ Keep out-of-range data ◇ Se	1986
Gray level multiplication	actor factor: 2.0
Current image:	THE RESERVE OF THE PARTY OF THE

Figure 12 The histograms window in CVIPtools offers nine methods for image enhancement.

tion's use. The example from the manual page can be copied directly and compiled to give the programmer an idea of how the function operates. For example, the manual page for the function *local histeq* looks like this:

local_histeq(3) C Library Functions
local_histeq(3)
NAME

local_histeq-performs histogram
equalization on block-by-block basis

SYNOPSIS

```
#include (stdio.h)
#include \'CVIPimage.h''
#include \'CVIPdef.h''
#include \'CVIPcolor.h''
#include \'CVIPhisto.h''
```

Image *local_histeq(Image *in, int
size, int mb)

⟨in⟩-pointer to an Image structure
⟨size⟩-desired blocksize
⟨mb⟩-RGB band on which to calculate
histogram (0, 1, 2)

PATH

\$CVIPHOME/HISTOGRAM/
local_histeq.c

DESCRIPTION

This function performs histogram equalization on local areas of an image rather than on the image as a whole. The user may specify the size of blocks to use. By performing local rather than global histeq, detail can often be enhanced in large uniform areas of an image.

The function will remap any INTEGER, FLOAT or DOUBLE image into SHORT. It operates directly on images of type SHORT and BYTE.

TYPES AND CONSTANTS
None

RETURN VALUES

A histogram-equalized image.

HISTORY

History information recorded: None

```
EXAMPLE
    #include (CVIPtoolkit.h)
    #include (CVIPdef.h)
    #include (CVIPimage.h)
    #include (CVIPconvert.h)
    #include \`CVIPcolor.h''
    #include \'CVIPhisto.h''
   void main ()
   Image *cvipImage;
   IMAGE FORMAT format;
   char *inputfile, *outputfile;
    (void) setDisplay Image
    (''picture'');
   print CVIP(''\n\t\tEnter the In-
   put File Name: '');
   inputfile = (char *) getString
   CVIP();
   format = getFormat CVIP (inputfile);
   cvipImage = read_Image(inputfile,
   format, 1);
   view Image(cvipImage, inputfile);
   cvipImage
              =
                   (Image
                                local
   histeq(cvipImage, 16, 0);
   cvipImage
              = remap Image(cvipIm-
   age, BYTE, 0, 255);
   print CVIP ( ' '\n\t\tEnter the Out-
   put File Name: '');
   outputfile = getString CVIP();
   view Image(cvipImage, outputfile);
   write Image (cvipImage, outputfile,
   FALSE, FALSE, format, 1);
   free (inputfile);
   free (outputfile);
BUGS
 None at this time
SEE ALSO
libhisto
AUTHOR
 Copyright (C) 1996 SIUE-by Scott Um-
```

Students refer to manual pages during creation of their final project in undergraduate and graduate imaging courses. Students are required to choose an

baugh and Arve Kjoelen.

area of interest, design experiments to pursue, define C functions to implement their experiments, and then code, debug, and test their algorithms. The sample menu-driven program provided to them, CVIPlab, is extended to include their own algorithms. Because CVIPtools' libraries can be linked to stand-alone programs, the amount of code written is minimal.

CONCLUSIONS

CVIPtools is a powerful collection of computer imaging tools, accessible through an easy-to-use graphical interface. The program allows students to see the results of performing both basic and advanced operations on digital images, and allows for easy experimentation that quickly answers the "what-if" questions that arise during the learning process. Because no specific knowledge of computer imaging is required for use of the program, people with interests as varied as cartography and graphic design are finding useful features within CVIPtools. The continual upgrading of the software will add to its usefulness for an ever-increasing range of users.

ACKNOWLEDGMENTS

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BIOGRAPHIES



Mark Zuke received BS and MS degrees in electrical engineering from Southern Illinois University at Edwardsville in 1994 and 1997, respectively. As a research assistant to Dr. Umbaugh, he designed and implemented the first version of the graphical user interface for CVIPtools. In addition, he created and maintained the primary documentation for the software in the form of UNIX man

pages. Since one of his interests is photography, he created many of the original photographs, as well as the final figures for Dr. Umbaugh's book, *Computer Vision and Image Processing: A Practical Approach Using CVIPtools*. He can be reached at the Electrical Engineering Department at SIUE, or at mzuke@ee. siue.edu.



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from the University of Missouri-Rolla, where he was a Chancellor's Fellow. He worked in industry as a computer design engineer from 1981 through 1986, and he has worked as a computer imaging consultant since 1986. He currently serves on the editorial board for IEEE Engineering in Medicine in Biology Magazine and the Pattern Recognition journal. His professional interests include artificial intelligence, computer vision and image processing, medical applications of image processing, and engineering design education. He has authored numerous papers, coauthored two book chapters, and recently written a book to be published by Prentice Hall PTR, entitled Computer Vision and Image Processing: A Practical Approach Using CVIPtools. Dr. Umbaugh is also the primary developer of the CVIPtools software package. He can be reached at the Department of Electrical Engineering, Southern Illinois University at Edwardsville, Edwardsville, IL 62026-1801, or at sumbaug@ee.siue.edu.