# On the moduli space of triply periodic minimal surfaces 

Adam G. Weyhaupt<br>joint work with Matthias Weber (Indiana University)

Department of Mathematics and Statistics Southern Illinois University Edwardsville

Joint Meetings, San Diego January 7, 2008

## Definition of a minimal surface

A minimal surface is a 2 -dimensional surface in $\mathbb{R}^{3}$ with constant mean curvature $H \equiv 0$.


## Definition of triply periodic minimal surface

A triply periodic minimal surface is a minimal surface $M$ immersed in $\mathbb{R}^{3}$ that is invariant under the action of a rank 3 lattice $\wedge$.


If $M$ is embedded, the quotient $M / \Lambda \subset \mathbb{R}^{3} / \Lambda$ is compact.

## Large family of examples

Since $M / \Lambda$ is compact (for an embedded TPMS $M$ ), it has a well-defined (finite) genus.

Theorem (Meeks '75)
Every TPMS in $\mathbb{R}^{3}$ has genus at least 3.
Many classical examples have genus 3.

## Schwarz P surface



## Schwarz H surface



## Schwarz H surface



## Schwarz P surface



## CLP surface



## CLP surface



## Previous moduli space results

Theorem (Meeks '75)
There is a continuous 5-parameter family of embedded triply periodic minimal surfaces of genus 3 in $\mathbb{R}^{3}$.
There are many surfaces not in Meeks' family: for example, the H surface family, the gyroid, and the Lidinoid.
Theorem (W '06)
There is a one parameter family of embedded TPMS of genus 3
that contains the Lidinoid and a one parameter family of embedded TPMS of genus 3 that contains the Lidinoid. None of these surfaces are in Meeks' family.

Theorem (Weber '07)
There is a 2 parameter family of embedded surfaces that
contains the H surface.

## Previous moduli space results

Theorem (Meeks '75)
There is a continuous 5-parameter family of embedded triply periodic minimal surfaces of genus 3 in $\mathbb{R}^{3}$.
There are many surfaces not in Meeks' family: for example, the H surface family, the gyroid, and the Lidinoid.

Theorem (W. '06)
There is a one parameter family of embedded TPMS of genus 3 that contains the Lidinoid and a one parameter family of embedded TPMS of genus 3 that contains the Lidinoid. None of these surfaces are in Meeks' family.
$\square$
There is a 2 parameter family of embedded surfaces that contains the H surface.

## Previous moduli space results

Theorem (Meeks '75)
There is a continuous 5-parameter family of embedded triply periodic minimal surfaces of genus 3 in $\mathbb{R}^{3}$.
There are many surfaces not in Meeks' family: for example, the H surface family, the gyroid, and the Lidinoid.
Theorem (W. '06)
There is a one parameter family of embedded TPMS of genus 3 that contains the Lidinoid and a one parameter family of embedded TPMS of genus 3 that contains the Lidinoid. None of these surfaces are in Meeks' family.

Theorem (Weber '07)
There is a 2 parameter family of embedded surfaces that contains the H surface.

## Previous moduli space results

Theorem (Meeks '75)
There is a continuous 5-parameter family of embedded triply periodic minimal surfaces of genus 3 in $\mathbb{R}^{3}$.
There are many surfaces not in Meeks' family: for example, the H surface family, the gyroid, and the Lidinoid.

## Theorem (W. '06)

There is a one parameter family of embedded TPMS of genus 3 that contains the Lidinoid and a one parameter family of embedded TPMS of genus 3 that contains the Lidinoid. None of these surfaces are in Meeks' family.

Theorem (Weber '07)
There is a 2 parameter family of embedded surfaces that contains the $H$ surface.

## A full understanding of a (small part of) moduli space

## Theorem

Let $M$ be an embedded, genus 3, TPMS in $\mathbb{R}^{3}$ that is invariant under an order 3 rotational symmetry. Then $M$ is a surface in one of the $r \mathrm{H}, \mathrm{rPD}$, or $r G L$ families. (In particular, the rG and $r L$ families coincide.)

The picture shows moduli space, parameterized using marked tori and the upper half-plane.


The rH family

The rPD family

The rGL family

## Parameterizing surfaces with tori

Let $M / \Lambda$ be an embedded genus 3 TPMS invariant under an order 3 rotation $\rho$. The map

$$
\rho: M / \Lambda \rightarrow M / \Lambda / \rho
$$

is a 3-fold branched covering map.

By Riemann-Hurwitz there are exactly 2 branch points and $M / \Lambda / \rho$ has genus 1 ; these fixed points of $\rho$ are exactly where the surface normal is vertical.

All minimal surfaces are completely determined by a Riemann surface $X$, a Gauss map $G$ (stereographic projection of the normal) and their "height differential" $d h$ (a holomorphic 1-form).

## Parameterizing surfaces with tori

Let $M / \Lambda$ be an embedded genus 3 TPMS invariant under an order 3 rotation $\rho$. The map

$$
\rho: M / \Lambda \rightarrow M / \Lambda / \rho
$$

is a 3-fold branched covering map.

By Riemann-Hurwitz there are exactly 2 branch points and $M / \Lambda / \rho$ has genus 1 ; these fixed points of $\rho$ are exactly where the surface normal is vertical.

All minimal surfaces are completely determined by a Riemann surface $X$, a Gauss map $G$ (stereographic projection of the normal) and their "height differential" $d h$ (a holomorphic 1-form)

## Parameterizing surfaces with tori

Let $M / \Lambda$ be an embedded genus 3 TPMS invariant under an order 3 rotation $\rho$. The map

$$
\rho: M / \Lambda \rightarrow M / \Lambda / \rho
$$

is a 3-fold branched covering map.

By Riemann-Hurwitz there are exactly 2 branch points and $M / \Lambda / \rho$ has genus 1 ; these fixed points of $\rho$ are exactly where the surface normal is vertical.

All minimal surfaces are completely determined by a Riemann surface $X$, a Gauss map $G$ (stereographic projection of the normal) and their "height differential" $d h$ (a holomorphic 1-form).

## Height differential

$d h$ is invariant under $\rho$ (we have oriented the surface so that the axis of $\rho$ is vertical). Therefore, $d h$ descends as a holomorphic 1 -form to the torus. Since up to a constant there is only one holomorphic 1 -form on a torus,

$$
d h=r e^{i \theta} d z
$$

Changing $r$ simply dilates the surface in space. $\theta$ is the "angle of association" and is used to solve the period problem.

## Gauss map

$G$ is not invariant, but $G^{3}$ is invariant under $\rho$. One can see that $G^{3}$ has double order zeros (poles) at the branch points. Also, $G^{3}$ is well-defined on the torus (so is doubly periodic). By Liouville's theorem,

$$
G^{3}=\lambda e^{i \varphi} \frac{\theta_{11}(z, \tau)}{\theta_{11}(z-a, \tau)}
$$

Adjusting $\varphi$ simply rotates the surface in space. $\lambda$ is the so-called Lopez-Ros factor and is used to solve the period problem.

## Summary of the parameterization

Any genus 3 , triply periodic minimal surface that is invariant under an order 3 rotation is determined by the following (real) parameters:


## Future work

1. Tie up some of the loose ends for order 3 case
> 2. The case of order 2 invariant surfaces is more difficult. Here, the branch points are not as tightly constrained by Abel's formula, so one gets additional parameters. Two dimensional families seem to occur.

## Future work

1. Tie up some of the loose ends for order 3 case
2. The case of order 2 invariant surfaces is more difficult. Here, the branch points are not as tightly constrained by Abel's formula, so one gets additional parameters. Two dimensional families seem to occur.
